

RESEARCH INTEREST

 DEEP SPACE EXPLORATION AND SPACE MISSION DESIGN ASTROPHYSICS AND ASTRODYNAMICS 	 Spacecraft Design Sensor Fusion 	
DUCATION		
UNIVERSITY OF TEHRAN	2019-2021(exp)	
M.Sc. Space Engineering GPA = 4/4		
 Ranked 1st Universities in Iran based on UsNews 		
ACADEMIC CENTER FOR EDUCATION, CULTURE AND RESEARCH (ACECR)	2019-2020	

HEALTHCARE-MBA GPA = 4/4	
AVIATION INDUSTRY TRAINING CENTER (AITC)	2016-2019
B. Eng. Avionics Technology Engineering GPA 3.8/4	
CIVIL AVIATION TECHNOLOGY COLLEGE (CATC)	2013-2016

A.E.T. AIRCRAFT AVIONICS

SELECTED COURSES __

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UNIVERSITY OF TEHRAN Advanced Orbit Mechanics | 3.57/4 Spacecraft System Design | 3.3/4 Academic Center for Education, Culture and Research (ACECR) Project Management | 3.96/4 Human Resource Management | 3.84/4 Problem Solving | 3.68/4 Aviation Industry Training Center (AITC) Safety Management System | 3.9/4 Reliability in Aviation Industry | 3.7/4 Civil Aviation Technology College (CATC) Aircraft Computer | 4/4

TEACHING EXPERIENCE

AVIATION INDUSTRY TRAINING CENTER (AITC) INTERN AS ANDROID DEVELOPER INTERNSHIP INSTRUCTOR, B.ENG. AVIONICS TECHNOLOGY | 2020 INTERNSHIP INSTRUCTOR, B.ENG. AIRCRAFT MAINTENANCE | 2019-2020 INTERNSHIP INSTRUCTOR, A.E.T AVIONICS | 2018-2020 INTERNSHIP INSTRUCTOR, A.E.T AIRCRAFT MAINTENANCE | 2018-2020 LAB INSTRUCTOR, ELECTRONIC 1 | 2019-2020 LAB INSTRUCTOR, ELECTRONIC 2 | 2019-2020 LAB INSTRUCTOR, ELECTRONIC 3 | 2019-2020 LAB INSTRUCTOR, ELECTRONIC CIRCUITS 1 | 2019-2020 LAB INSTRUCTOR, ELECTRONIC CIRCUITS 2 | 2019-2020 LAB INSTRUCTOR, ELECTRONIC CIRCUITS 2 | 2019-2020 LAB INSTRUCTOR, MICROPROCESSORS | 2019-2020 LAB INSTRUCTOR, AIRCRAFT INSTRUMENTS | 2019-2020 2018-2020

SEARCH EXPERIENCE	
THESIS CONSULTANT AVIATION INDUSTRY TRAINING CENTER	2018-202
DESIGN AND IMPLEMENTATION OF A 3 AXIS CNC MACHINE	
DESIGN AND IMPLEMENTATION OF A CNC HOT WIRE	
DESIGN AND IMPLEMENTATION OF PULSE CIRCUITS TRAINING BOARD	
DESIGN, SIMULATE AND BUILD AN AIRCRAFT FIRE EXTINGUISHING SYSTEMS	
DESIGN AND IMPLEMENTATION OF RETRACTABLE LANDING GEAR	
Former of Fuzzy Logic Lab Interest Group	202
UNIVERSAL SCIENTIFIC EDUCATION AND RESEARCH NETWORK (USERN)	
AIRCRAFT DESIGN SHARIF UNIVERSITY OF TECHNOLOGY (SUT)	202
ShadX Team Leader	
AIAA Aircraft Design Competition	
Referee of research council	2019-Presen
STUDENT'S SCIENTIFIC RESEARCH CENTER (SSRC)	
THREE DEGREES OF FREEDOM TESTBED FOR CUBESAT UNIVERSITY OF TEHRAN (UT)	201
ATTITUDE DYNAMICS, DETERMINATION, AND CONTROL	
Using LabView to control and monitor the satellite attitude parameter	
DESIGN AFFORDABLE 3-AXIS CNC CO2 LASER CUTTING MACHINE	2019-202
CAD Design using: Inventor and SolidWorks	
DESIGN AND IMPLICATION OF REMOTE SENSING-COMMUNICATIONS CANSAT	2019-202
UNIVERSITY OF TEHRAN (UT)	
CAD Design using: Inventor and SolidWorks	
 Design and Implication of Network Communication using Arduino and ZigBee Module for TT8 	δC
 Use Raspberry Pi for Computer Vision and Pattern Detection 	
 INS-GPS Integration for Navigation Parameter Estimation 	
 Sensor Fusion for Estimating Environmental Parameters 	
DESIGN AND FABRICATION OF 3-AXIS CNC MILLING MACHINE	2019-202
CAD DESIGN USING INVENTOR AND SOLIDWORKS	
 Use Arduino and RAMPS to Control the CNC Machine 	
• USE MACH3, POWERMILL, EDGE CAM, SOLIDWORKS AND GRBL AS MACHINE CONTROL AND CAM SOFTWARE	
Design and Implication of Scientific-Exploration CanSat	2019-202
UNIVERSITY OF TEHRAN (UT)	
CAD DESIGN USING: INVENTOR AND SOLIDWORKS	
DESIGN AND IMPLICATION OF NETWORK COMMUNICATION USE ARDUINO AND ZIGBEE MODULE FOR TT&C	
INS/GPS Integration for Navigation Parameter Estimation	
Sensor Fusion for Estimating Environmental Parameters	
DESIGN MICRO MILLING MACHINE FOR PROTOTYPING MICROFLUIDIC DEVICES	2019-202
DESIGN AND SIMULATION OF MECHANICAL STRUCTURE USING SOLIDWORKS, ANSYS AND INVENTOR	
DESIGN AND SIMULATION OF CONTROL CIRCUIT	
	2018-202
AVIATION INDUSTRY TRAINING CENTER (AITC)	
DESIGN AND FABRICATION OF AVIONICS SIMULATION SYSTEM	2018-201
CIRCUIT DESIGN USING: ALTIUM DESIGNER, PROTEUS AND SOLIDWORKS ELECTRICAL	2010 201
• Iran University of Science and Technology	2018-201
Circuit Design Using Altium Designer	
 Circuit Analysis and Simulation Using ADS, Ansys and CST 	

• Electromagnetic Analysis and Simulation Using COMSOL, ANSYS and CST

LAB EXPERIENCES		
SPACE LAB UNIVERSITY		2019-Present
FUZZY LOGIC LAB UNIV		2020-Present
AVIONICS LAB AVIATION INDUSTRY TRAINING CENTER		2018-2020
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AIRCRAFT INSTRUMENT	CIVIL AVIATION AND TECHNOLOGY	2014-2016
ÍNTERNSHIPS		
IRANAIR		2018
 Avionics Internship 		
CIVIL AVIATION TECHNO	LOGY COLLEGE	2016
 Avionics Internship 		
AVIATION INDUSTRY TRA	INING CENTER	2018
 Avionics Internship I 		
• Avionics Internship II		
PUBLICATIONS		
FORMATION CONTROL UT	ILIZING RECEDING HORIZON ITERATIVE LEARNING CONTROL	Under Review
AUTOMATICA (JOURNAL OF	IFAC)	
NEURAL NETWORK BASE	D ESTIMATION: A REVIEW	in prep
 Information Fusion 		
Skills		
PROGRAMMING LANGUAGES	<i>Experienced:</i> MATLAB Arduino <i>Familiar:</i> Python C++ LabView ROS Simulink LaTex	
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM	<i>Experienced:</i> MATLAB Arduino <i>Familiar:</i> Python C++ LabView ROS Simulink LaTex <i>Familiar:</i> Jupyter Matplotplib Numpy Pandas Scikit-learn K	CAD
Programming Languages Frameworks & Libraries CAD-CAM CAE	Experienced:MATLAB ArduinoFamiliar:Python C++ LabView ROS Simulink LaTexFamiliar:Jupyter Matplotplib Numpy Pandas Scikit-learn KCATIA SolidWorks Inventor Proteus Altium Designer Autoo	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn k CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict I • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS	 Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn k CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM Time Management, Punctuality, Extremely Coordinated and Goal-D Project Management, Teamwork, Team Management and Conflict I Multi-Tasking, Multi-Tasking, Flexibility and Adaptation Problem Solving 	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS	 Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn k CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM Time Management, Punctuality, Extremely Coordinated and Goal-D Project Management, Teamwork, Team Management and Conflict I Multi-Tasking, Multi-Tasking, Flexibility and Adaptation Problem Solving 	CAD SOL HFSS Directed Resolution
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PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS CERTIFICATES NIGHTSKY INSTITUTE • ASTRONOMY I	 Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn k CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM Time Management, Punctuality, Extremely Coordinated and Goal-D Project Management, Teamwork, Team Management and Conflict I Multi-Tasking, Multi-Tasking, Flexibility and Adaptation Problem Solving 	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS CERTIFICATES NIGHTSKY INSTITUTE • ASTRONOMY I • ASTRONOMY II UNIVERSITY OF TORONTO	 Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn k CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM Time Management, Punctuality, Extremely Coordinated and Goal-D Project Management, Teamwork, Team Management and Conflict I Multi-Tasking, Multi-Tasking, Flexibility and Adaptation Problem Solving 	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS CERTIFICATES NIGHTSKY INSTITUTE • ASTRONOMY I • ASTRONOMY I UNIVERSITY OF TORONTC • STATE ESTIMATION AND LO	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn K CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict I • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS CERTIFICATES NIGHTSKY INSTITUTE ASTRONOMY I ASTRONOMY I UNIVERSITY OF TORONTC STATE ESTIMATION AND LO IRANAIR	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn K CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM: • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict I • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS CATES NIGHTSKY INSTITUTE ASTRONOMY I ASTRONOMY I UNIVERSITY OF TORONTC STATE ESTIMATION AND LO IRANAIR AVIONICS INTERNSHIP TRAI	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn K CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM: • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict I • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS SOFT SKILLS CERTIFICATES NIGHTSKY INSTITUTE ASTRONOMY I ASTRONOMY I ASTRONOMY I STATE ESTIMATION AND LO IRANAIR AVIONICS INTERNSHIP TRAI ÉCOLE POLYTECHNIQUE	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn k CATIA SolidWorks Inventor Proteus Altium Designer AutoO CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict I • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS SOFT SKILLS CERTIFICATES NIGHTSKY INSTITUTE • ASTRONOMY I • ASTRONOMY I UNIVERSITY OF TORONTC • STATE ESTIMATION AND LO IRANAIR • AVIONICS INTERNSHIP TRAI ÉCOLE POLYTECHNIQUE • HOW TO WRITE AND PUBLI	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn K CATIA SolidWorks Inventor Proteus Altium Designer Autoor CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM: • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict I • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving CALIZATION FOR SELF-DRIVING CARS NING SH A SCIENTIFIC PAPER	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS CERTIFICATES NIGHTSKY INSTITUTE ASTRONOMY I ASTRONOMY I ASTRONOMY I UNIVERSITY OF TORONTC STATE ESTIMATION AND LO IRANAIR AVIONICS INTERNSHIP TRAI ÉCOLE POLYTECHNIQUE HOW TO WRITE AND PUBLI NATIONAL SOCIETY OF P	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn k CATIA SolidWorks Inventor Proteus Altium Designer AutoO CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict I • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving CALIZATION FOR SELF-DRIVING CARS	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS CERTIFICATES NIGHTSKY INSTITUTE ASTRONOMY I ASTRONOMY I ASTRONOMY II UNIVERSITY OF TORONTCO STATE ESTIMATION AND LO IRANAIR AVIONICS INTERNSHIP TRAI ÉCOLE POLYTECHNIQUE HOW TO WRITE AND PUBLI NATIONAL SOCIETY OF P	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn K CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM: • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict II • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving CALIZATION FOR SELF-DRIVING CARS NING SH A SCIENTIFIC PAPER ROFESSIONAL ENGINEERS	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS OFT SKILLS CATES NIGHTSKY INSTITUTE ASTRONOMY I ASTRONOMY I ASTRONOMY II UNIVERSITY OF TORONTC STATE ESTIMATION AND LO IRANAIR AVIONICS INTERNSHIP TRAI ÉCOLE POLYTECHNIQUE HOW TO WRITE AND PUBLI NATIONAL SOCIETY OF P BRIDGING THE GAP TO LEA	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn K CATIA SolidWorks Inventor Proteus Altium Designer Autoo CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM: • Time Management, Punctuality, Extremely Coordinated and Goal-D • Project Management, Teamwork, Team Management and Conflict II • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving CALIZATION FOR SELF-DRIVING CARS NING SH A SCIENTIFIC PAPER ROFESSIONAL ENGINEERS	CAD SOL HFSS Directed Resolution
PROGRAMMING LANGUAGES FRAMEWORKS & LIBRARIES CAD-CAM CAE SOFT SKILLS SOFT SKILLS ERTIFICATES NIGHTSKY INSTITUTE • ASTRONOMY I • ASTRONOMY I • ASTRONOMY I UNIVERSITY OF TORONTC • STATE ESTIMATION AND LO IRANAIR • AVIONICS INTERNSHIP TRAI ÉCOLE POLYTECHNIQUE • HOW TO WRITE AND PUBLI NATIONAL SOCIETY OF P • BRIDGING THE GAP TO LEA MATHWORKS	Experienced: MATLAB Arduino Familiar: Python C++ LabView ROS Simulink LaTex Familiar: Jupyter Matplotplib Numpy Pandas Scikit-learn k CATIA SolidWorks Inventor Proteus Altium Designer AutoC CST ADS ANSYS Workbench ANSYS Electrical Abaqus COM • Time Management, Punctuality, Extremely Coordinated and Goal-E • Project Management, Teamwork, Team Management and Conflict I • Multi-Tasking, Multi-Tasking, Flexibility and Adaptation • Problem Solving Calization For Self-Driving Cars NING SH A SCIENTIFIC PAPER ROFESSIONAL ENGINEERS DERSHIP: CONNECTING THE SKILLS YOU HAVE WITH THE SKILLS YOU NEED	CAD SOL HFSS Directed Resolution

• 3^{rd} Grade Coaching

MEMBERSHIP __

MEMBER OF RESEARCH COUNCILStudent's Scientific Research Center (SSRC)MEMBERInternational Association of Engineers (IAENG)MENTORSpace Generation Advisory Council (SGAC)GRADUATE STUDENT MEMBERSHIPAmerican Physical Society (APS)STUDENT AFFILIATERoyal Aeronautical Society (RAeS)STUDENT MEMBERSpace & Satellite Professionals International (SSPI)STUDENT MEMBERInstitute of Mathematical StatisticsE-STUDENTRoyal Statistical SocietyMEMBERArt in Medical Education - Educational Development Center (EDC) - TUMSMEMBERFuzzy Logic Lab USERN Interest GroupMEMBER OF R&D TEAMUSERN

WORK EXPERIENCE

MANAGER	2013-Present
• Arman Imen Passargad, Tehran, Iran	
INSTRUCTOR	2018-Present
 Aviation Industry Training Center, Tehran, Iran 	
EMPLOYEE	2019-2020
• Tucan Maham Fan, Tehran, Iran	
Martial Arts Instructor	2015-Present
IRAN MARTIAL ARTS FEDERATION, TEHRAN, IRAN	
Accountant	2013-2017
• Chopin Restaurant, Tehran, Iran	
Accountant	2011
• Agah Taraz Argham, Tehran, Iran	

ACADEMIC PROJECTS

QUANTUM COMPUTER (SEMINAR)	2020
QUANTUM COMPUTATION ALGORITHM	
QUANTUM COMPUTERS IMPLICATION METHODS	
CONCEPTUAL DESIGN AND MISSION ANALYSIS OF FIRESAT	2020
USING ECSS DOCUMENTS	
 CAD Design, Layout Optimization, and Thermodynamic Analysis 	
UNIVERSITY OF TEHRAN	
DETERMINE SATELLITE'S POSITION, VELOCITY, AND ORBIT (IN 3D)	2020
 Use Initial Vector (r0 & v0) as Input in MATLAB 	
• University of Tehran	
Modeling and Simulation of Aerospace Vehicle Dynamics 5 DoF Simulation	2020
USING CADAC++	
• University of Tehran	
Design, Analysis, and Build RC airplane	2015
 CAD Design: SolidWorks, CATIA, and Inventor 	
• CAE Analysis: ANSYS, xflr5	
CIVIL AVIATION TECHNOLOGY COLLEGE	
Ultra-Sonic Distance Measuring	2014
CIVIL AVIATION TECHNOLOGY COLLEGE	
VLF RADIO TELESCOPE	2013
CIVIL AVIATION TECHNOLOGY COLLEGE	

XECUTIVE ACTIVITIES <u>Member of 4th Student Education Development Festival</u>	202
EDUCATION DEVELOPMENT CENTER (EDC) TUMS	202
MEMBER OF LAB TECHNIQUES SCHOOL EXECUTIVE TEAM	202
UNIVERSAL SCIENTIFIC EDUCATION AND RESEARCH NETWORK (USERN)	202
MEMBER OF MTALK EXECUTIVE TEAM	202
UNIVERSAL SCIENTIFIC EDUCATION AND RESEARCH NETWORK (USERN)	202
MEMBER OF ART IN MEDICAL EDUCATION WORKING GROUP	202
EDUCATION DEVELOPMENT CENTER (EDC) TUMS	202
THE CORE MEMBER OF PUBLICITY TEAM	202
UNIVERSAL SCIENTIFIC EDUCATION AND RESEARCH NETWORK (USERN)	202
THE CORE MEMBER OF MEDIA TEAM	202
UNIVERSAL SCIENTIFIC EDUCATION AND RESEARCH NETWORK (USERN)	202
THE CORE MEMBER OF GRAPHIC AND DESIGN TEAM	202
	202
UNIVERSAL SCIENTIFIC EDUCATION AND RESEARCH NETWORK (USERN) THE CORE MEMBER OF IT TEAM	202
UNIVERSAL SCIENTIFIC EDUCATION AND RESEARCH NETWORK (USERN)	202
	201
FORMER OF CULTURAL SOCIETY KARA	201
FACULTY OF NEW SCIENCES AND TECHNOLOGY UNIVERSITY OF TEHRAN (UT)	204
ORGANIZER OF CLIMATE CHANGE CONFERENCES	201
• FACULTY OF NEW SCIENCES AND TECHNOLOGY UNIVERSITY OF TEHRAN (UT)	
THE 23 rd CONFERENCE OF ANNUAL GENERAL MEETING	20
STUDENT SCIENTIFIC RESEARCH CENTER, TEHRAN UNIVERSITY OF MEDICAL SCIENCES	
NURSING AND MIDWIFERY SCHOOL, TEHRAN UNIVERSITY OF MEDICAL SCIENCE	
World Astronomy Week	201
• NIGHTSKY INSTITUTE MINA DOME, TEHRAN, IRAN	
ORGANIZER OF WATERROCKET COMPETITION	201
CIVIL AVIATION TECHNOLOGY COLLEGE	
The 21 st conference of Annual General Meeting	201
 Student Scientific Research Center, Tehran University of Medical Sciences 	
 NURSING AND MIDWIFERY SCHOOL, TEHRAN UNIVERSITY OF MEDICAL SCIENCE 	
The 5 th International Aviation & Space Industries Exhibition of Iran	201
CIVIL AVIATION TECHNOLOGY COLLEGE (CATC)	
The 20 th conference of Annual General Meeting	201
 Student Scientific Research Center, Tehran University of Medical Sciences 	
 NURSING AND MIDWIFERY SCHOOL, TEHRAN UNIVERSITY OF MEDICAL SCIENCE 	
THE 4 th INTERNATIONAL AVIATION & SPACE INDUSTRIES EXHIBITION OF IRAN	201
CIVIL AVIATION TECHNOLOGY COLLEGE (CATC)	
ROAD URBAN DEVELOPMENT & THE RELATED INDUSTRIES EXHIBITION	201
CIVIL AVIATION TECHNOLOGY COLLEGE (CATC)	
THE 3 rd INTERNATIONAL AVIATION & SPACE INDUSTRIES EXHIBITION OF IRAN	201
CIVIL AVIATION TECHNOLOGY COLLEGE (CATC)	
DLUNTEER WORK	
THE 7 th INTERNATIONAL FESTIVAL OF PAINTINGS FOR PEDIATRIC PATIENTS (IFPPP)	202
Health And Art (HEART) USERN	202
SPACE GENERATION ADVISORY COUNCIL	2020-Prese
MENTOR	2020-11838
KAHRIZAK NURSING HOME FOR THE ELDERLY AND THE DISABLED	2013-Prese
Pest Control	2013-51656

PEST CONTROL

SARAI EHSAN SOCIAL VICTIMS CENTER • PEST CONTROL	2013-Present
Vardavard Welfare	2013-Present
PEST CONTROL	
TEHRAN FOUNDATION FOR THE MENTALLY HANDICAPPED	2013-Present
Pest Control	
Kamraniyeh Charity Foundation	2013-Present
Pest Control	
Awards & Honors	
Appreciated Presenter	2021
USERN MINIATURE TALK	
MARTIAL ARTS FEDERATION - NATIONAL COMPETITIONS	
GOLD MEDALIST 2019	
GOLD MEDALIST 2018	
GOLD MEDALIST 2012	
Gold Medalist 2011	
SILVER MEDALIST 2015	
BRONZE MEDALIST 2019	
BRONZE MEDALIST 2016	

NEARU MARTIAL ARTS

• Black Belt Dan 2^{nd}

6 of <mark>6</mark>

2019